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Carbon epoxy composites thermal conductivity at 80 K and 300 K

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I. Introduction

The new microsatellite launchers technology with liquid or hybrid propulsion needs very light devices including the oxygen cryogenic tank-that are one of the most part of the complete system. Whereas metals were extensively used as tank materials^{1,2}, the composite technology appears more promising but also raises new technological challenges. The main one is related to its compability with the liquid ergol. to tThe ignition and combustion of the carbon-epoxy material in contact with the liquid oxygen³ is a part of this challenge. The oxygen tank pressure⁴, the oxygen concentration^{5,6,7}, and temperature⁸ are keys parameters in the ignition and combustion processes. Temperature increase can be originated from multiple phenomena as: a particle impact¹, a fast liquid compression⁹, friction¹ between liquid and solid wall or mechanical resonance due to vibrations¹. The main drawback of composites is their low performance with respect to combustion. The process of polymer matrix decomposition is the major factor to trigger the ignition. However the fiber is also highly responsible in the heat transfer within the heating area. Gerzeski¹⁰ found that most of metallic materials (aluminium alloys, nickel) satisfies the mechanical impact test due to their high thermal conductivity at temperature of -196 ° C (77K). This has led to the development of composite materials with the same resin, and different fibers^{10,11,12}. Therefore, composites capable of meeting the compatibility liquid oxygen standard must have high ignition temperature of the resin and a high thermal conductivity of the composite, and therefore of the fiber.

This study focuses on the thermal conductivity measurement of three composites constituted from the same epoxy resin (5052-4 RTM BMI) and different carbon fibers, namely the XN15, YSH70 and CN90. Each composites samples are removed from a plate in the form of cylindrical samples of $R=1.5$ cm and thickness $e=3$ mm. Each sample is constituted from the same number of folds (about 40) and the winding process lead to orientate the fibers in the [-45, 0, 45, 90]°, which allows to assume homogenous In-plane properties. The measured density of the fibers and the resin are reported in Tab. 1. As reported in the paper of Reed and Golda¹⁴, epoxy resins contract from 0.85 to 1.2 % on cooling from 300 to $4\overline{\text{K}}$. Therefore the density will be further considered as a constant on the [300-77] K temperature range. On the other hand, the coefficient thermal expansion in the same temperature range is lower than 0.5×10^{-6} K⁻¹. Therefore, the fiber density will be considered as a constant. The measured composite density differs less than 4% from the calculated value starting from the fiber volume fraction. It means that the volume fraction is slightly higher than the real value.

As reported in ^{13,14}, the specific heat of epoxy is 1110 $J.kg^{-1}.K^{-1}$ at 300 K and it is about 380 $J.kg^{-1}.K^{-1}$ à 77 K. In addition, the specific heat of graphite is ¹⁵ 644 J.kg⁻¹.K⁻¹ at 300 K and it is about 109 $J.kg^{-1}.K^{-1}$ at 77 K.

The specific heat of the composite has been measured at 300 K and it is calculated starting from the fiber volume fraction *f*. The results are reported in the first column of Tab. 2. A very slight difference (less than 2%) appears that comes, as also reported for the density, from a very small overestimation of the fiber volume fraction. The specific heat of the composite at **Mis en forme :** Exposant

77 K is then calculated starting from the values for the carbon fiber and the resin at that temperature and also from the fiber volume fraction with 2% correction term. Results are reported in the second column of Tab. 2.

Tab. 1. Measured density of the fiber and the resin at 300 K and 77 K, measured thermal conductivity of the fiber at 300K and measured composite density at 300 K with comparison with the calculated one.

Tab. 2. Measured/calculated specific heat in $[I.K^{-1} \cdot kg^{-1}]$ of the three composites at 300 K. Calculated value at 77 K with 2% correction term coming from the fiber volume fraction overestimation.

The In-plane k_{\parallel} and transverse k_{\parallel} thermal conductivity are measured at 77K and 300K using

the hot disk technique. The thermal resistance R_c at the interface between the probe and the material is a key parameter that needs also to be identified as well as for the heat capacity of the probe. An inverse technique is implemented that lead to identify the unknown parameters based on experimental data and a heat transfer model consistent with the experiment. For information^{16,17}, the longitudinal thermal conductivity of the fibers at 300 K is reported in Tab. 1 and the thermal conductivity k_r of the epoxy resin is 0.1 W.m⁻¹.K⁻¹ at 80 K and it is 0.25 W.m⁻¹.K⁻¹ at 0.25300 K.

II. Thermal conductivity measurements

In-plane and transverse thermal conductivity of the composite are measured using a hot probe type method known as the hot disk technique^{18,19,20,21}. The sensor is made of nickel foil in the form of a bifilar spiral covered on both sides with an insulating layer of Kapton. The thicknesses of the foil and the Kapton layer are 10 and 25 µm, respectively, the effective diameter of the bifilar spiral is $r_0 = 3.189$ mm and the radius of the heating area is 20 mm.

The thermal sensor is placed between two pieces of the sample material and is then heated by a constant electrical current *i*. The probe constitutes both heat source and temperature sensor. The time-dependent resistance of the thermal probe sensor element, during the transient recording, is expressed as:

$$
R(t) = R_0(T_0)(1 + \vartheta(T_0) \mathsf{D} T(t))
$$

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(1)

where R_0 is the resistance of the probe element at the initial temperature T_0 , $\partial(T_0)$ is the temperature coefficient of resistance (TCR) that is calibrated prior to the experiment and $\Delta T(t)$ is the temperature increase of the probe during the heating.

The probe resistance R_0 and TCR α have been accurately measured for the temperature range of interest and data are reported in Tab. I.

Classical assumptions are that the heat flux related to the Joule's effect is uniform all over the probe area at each time *t* during the experiment and that it is measured the average temperature T of the probe.

To record the potential difference variations at the sensor, which normally are of the order of a few millivolts during the transient recording, a bridge arrangement is used in order to have a

current *i* holding constant through the probe.

Heat diffusion in the sample rests on the classical linear heat diffusion equation in cylindrical coordinates. Heat flux $j_0/2 = R_0 l^2/2$ is imposed at one face of the sample by the thermal probe, whereas the temperature at the other face is maintained at the constant value T_0 . It is finally assumed that the circumference area is perfectly insulated (in practice, the heating duration is chosen so that heat diffusion length does not exceed the sample radius *R*).

Using the experimental symmetry, it is allowed to consider only one of the two samples located at both sides of the thermal probe. Applying the Laplace transform on the time variable and the Hankel transform on the radial coordinate, an analytical expression for the spatial average sensor temperature *T*(*t*) is found as:

$$
\overline{T}(t) = L^{-1}\left(Z(p)\right)\frac{f_0}{2} \tag{2}
$$

In this relation p denotes the Laplace variable and $L^{-1}(\)$ is the inverse Laplace transform that is calculated from the de Hoog algorithm. The transfer function $Z(p)$ is given by :

$$
Z(p) = \frac{1}{p} \left(\frac{1}{C_s p + \frac{1}{R_s + F(p)}} \right),
$$
\n(3)

where C_s is the probe heat capacity that leads to a delay in the thermal response and R_c is the thermal contact resistance at the interface between the probe and the sample. Function $F(p)$ is given by:

$$
F(p) = \left(\frac{r_0}{R}\right)^2 F_0\left(\mathbf{a}_0, p\right) + \sum_{n=1}^N F_0\left(\mathbf{a}_n, p\right) \frac{4\left[\mathbf{J}_1\left(\mathbf{a}_n, r_0\right)\right]^2}{R^2 \mathbf{a}_n^2 \left[\mathbf{J}_0\left(\mathbf{a}_n, R\right)\right]^2},
$$
\n(4)

where J_0 $\big($ $\big)$ and J_1 $\big($ $\big)$ are the first and second order Bessel functions of second specie and:

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$$
F_{0}\left(\boldsymbol{a}_{n},\boldsymbol{p}\right)=\frac{1-\boldsymbol{\Theta}^{2b_{n}\boldsymbol{\Theta}}}{b_{n}k_{n}\left(1+\boldsymbol{\Theta}^{2b_{n}\boldsymbol{\Theta}}\right)}
$$

(5)

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(6)

(7)

With:

$\beta_n = \sqrt{a_n^2 \frac{k_{\parallel}}{k_{\perp}} + \frac{p \rho_c C_{p_c}}{k_{\perp}}}$

And:

$$
a_n = \begin{cases} 0 & \text{if } n = 0 \\ \rho \left(n + \frac{1}{4} \right) - \frac{3}{8\rho \left(n + \frac{1}{4} \right) R} & \text{if } n = 1, 2, 3, \dots \end{cases}
$$

In addition of the two thermal conductivity k_{\parallel} and k_{\parallel} , the probe capacity C_s and the thermal resistance R_c at the probe-sample interface are unknown. In order to assess the identification feasibility, the dimensionless sensitivity functions $X_q(t) = q \left[dT(t)/dq \right]$ for the four parameters $\theta = [k_{\parallel}, k_{\perp}, R_c, C_s]$ are calculated and plotted in Fig. 1.

Fig. 1. Dimensionless sensitivity for k_{\parallel} , k_{\parallel} , R_c and C_s according to $a_r t/R$. Numerical values for this simulation are: *R*=1.5 cm, *e*=3mm, $k_{\parallel} = 100 \text{ W.m}^{-1}.\text{K}^{-1}$, $k_{\lambda} = 3 \text{ W.m}^{-1}.\text{K}^{-1}$, $R_e = 10^{-4}$ K.m².W⁻¹, $C_s = 20$ J.K⁻¹.m⁻².

The sensitivity functions for the two thermal conductivities are not fully linear dependant (as also demonstrated by plotting their ratio in the inset of the figure). The sensitivity for C_s is close to zero on the quasi-total time range. Finally the sensitivity of the R_c varies only at the short times and then remains constant. As represented in the inset of the figure, the sensitivity functions for k_r and R_c are linear independant only at the first instants, which comrequires to identify both parameters separately considering the first part of the data.

Therefore, C_s is measured from an experiment with the probe alone at the two investigated temperatures (330 K and 77 K), for a given time step. It is found $C_s = 26 \pm 0.5$ J.K⁻¹ m⁻² at 300 K and $C_s = 20 \pm 0.5$ J.K⁻¹.m⁻² at 77 K and it is assumed that those values do not change significantly when the probe is inserted between both parts of the composite.

III. Results

 $S_{\overline{7}}^2 = J_{\min}/N$.

The sampling time interval is noted D*t* and the number of data is *N* for the duration of the experiment. The four parameters have been identified minimizing the objective function

 $J = \mathring{\Theta} e_i^2$ *i*=1 $\oint d^2 \vec{e}_i^2 = \oint d^2 \left(Y_i - \overline{T_i} \right)^2$ *i*=1 $\hat{\hat{A}}(\gamma - \overline{\tau_i})^2$, i.e., the quadratic <u>differencegap</u> between the measured temperature

 $Y_i = Y(iDt)$ and the simulated one T_i obtained from relation $(2)(2)$. The minimization is achieved using the Levenberg-Marquardt algorithm. Results are reported in Tab. II. The measured temperature and the simulated one starting from the identified parameters are plotted in Fig. II.

The fit between measures and simulations is almost perfect; the residuals are low with a whitewith noise featuring (the auto-correlation function being close to a Dirac function). The value of the objective function at the end of the identification process is less than 10^{-5} and the residuals do not reveal a bias in the heat transfer model. The standard deviations for the

identified parameters are classically calculated from: $S_q = \sqrt{(\mathbf{X}^T \mathbf{X})^2} S_{\overline{T}}^2$ with $\mathbf{X} = \begin{bmatrix} \mathbf{X}(k_1) & \mathbf{X}(k_2) & \mathbf{X}(R_3) & \mathbf{X}(C_3) \end{bmatrix}$ ëê ù where $\mathbf{X}(q)$ denotes the sensitivity vector, of length *N*, for $q = [k_1, k_2, R_c, C_s]$. Furthermore, the noise standard deviation is approximated from the value of the objective function J_{\min} at the end of the identification process as:

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Tab. 4. Identified In-plane and transverse thermal conductivity and thermal resistance at the interface between the material and the probe.

Fig. 2. First row: measured temperature $Y(t)$ during the transient hot disk experiment and simulated temperature $T(t)$ with identified parameters reported in Tab. 4 at 77 K and 300 K. Second row: residuals $e(t)$.

IV. Conclusions

The measured In-plane thermal conductivity of the three composites follows well the carbon fibre longitudinal thermal conductivity at room temperature. Obviously, the epoxy resin being less conductive than the fibre, the composite thermal conductivity is lower than that of the fibre itself. Using the classical mixing law for the in plane thermal conductivity it is found the theoretical value as: $k_{\parallel} = f k_f + (1 - f) k_r$. Using the fibre volume fraction, the longitudinal thermal conductivity of the fibre at 300 K in Tab. 1 and that of the resin at 300 K, we found the theoretical value of k_{\parallel} for the three composites at 300 K as: $k_{\parallel}^{th} = 1.925 \text{W} \cdot \text{m}^{-1} \cdot \text{K}^{-1}$ for the XN15/epoxy, $k_{\parallel}^{th} = 146.6 \text{ W.m}^{-1} \cdot \text{K}^{-1}$ for the YSH10/epoxy and $k_{\parallel}^{th} = 243 \text{ W.m}^{-1} \cdot \text{K}^{-1}$ for the CN90/epoxy. These values are consistent with the measured ones reported in Tab. 4. Using the measured values at 77 K, it comes that the thermal conductivity of the carbon fibrer can be estimated from the previous mixing law and the epoxy thermal conductivity at 77 K. We found: $k_{XNI5,77K} = 0.76 \text{ W.m}^{-1} \cdot \text{K}^{-1}$, $k_{YSH70,77K} = 47.74 \text{ W.m}^{-1} \cdot \text{K}^{-1}$ and $k_{CNI90,77K} = 81.77 \text{ W.m}^{-1} \cdot \text{K}^{-1}$. Ignition test realized on the three composites showed that only the CN90/epoxy passed the test. This suggests that the thermal conductivity of carbon/epoxy material for liquid oxygen storage purpose must be equal or greater than $k_{\parallel}^{min} = 50$ W.m⁻¹.K⁻¹.

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